

Certain Submanifolds of Hsu-structure Manifolds

Ram Nivas and Navneet Kumar Verma
Department of Mathematics and Astronomy,
Lucknow University - 226 007, India
Email: rnivas.lu@gmail.com
nk_v_11@rediffmail.com

Abstract

In this paper, authors have studied Hsu-structure manifolds and submanifolds. Submanifolds immersed in Hsu-structure manifold and $(f, g, A_1, A_2, T_1, T_2)$ - Hsu metric structure manifolds have been studied. Certain interesting results have been obtained.

1. Preliminaries

Let V_n be an n -dimensional differentiable manifold of class C^∞ . Suppose V_n is equipped with a tensor field F of type $(1, 1)$ such that

$$(1.1) \quad F^2 = a^r I$$

where 'a' is any real or complex number and r is a positive integer. Suppose further that V_n is equipped with a Riemannian metric G such that

$$(1.2) \quad G(FX, FY) = a^r G(X, Y).$$

Then V_n in view of (1.1) and (1.2) is said to possess a Hsu-metric structure [1]

Let V_m be an m -dimensional differentiable manifold equipped with a $(1, 1)$ tensor field f , vector fields T_1, T_2 and 1-forms A_1, A_2 such that

$$(i) \quad f^2 = a^r I + A_1 \otimes T_1 + A_2 \otimes T_2,$$

$$\begin{aligned}
 & \text{(ii)} \quad f T_1 = f T_2 = 0, \\
 (1.3) \quad & \text{(iii)} \quad A_1 \circ f = A_2 \circ f, \\
 & \text{(iv)} \quad A_i (T_j) + a^r \delta_{ij} = 0, \quad i, j = 1, 2 \\
 & \text{and} \\
 & \text{(v)} \quad \text{Rank } f = m - 2.
 \end{aligned}$$

Suppose further that there exists a Riemannian metric 'g' on V_m such that

$$(1.4) \quad g (fX, fY) = a^r g (X, Y) + A_1 (X) A_1 (Y) + A_2 (X) A_2 (Y) .$$

Obviously

$$(1.5) \quad g(X, T_1) = A_1 (X) \text{ and } g (X, T_2) = A_2 (X) .$$

On such a manifold V_m let for the Riemannian connection D

$$\begin{aligned}
 (1.6) \quad (D_X f)Y &= \{A_1(Y) + A_2(Y)\}X - 2 \{A_1(X)A_1(Y) + A_2(X)A_2(Y)\} (\lambda T_1 + \mu T_2) \\
 &+ g(X, Y) (\lambda T_1 + \mu T_2)
 \end{aligned}$$

is satisfied. Further let

$$(1.7) \quad D_X T_1 = -fX + \lambda T_2, \quad D_X T_2 = fX + \mu T_1.$$

Then we say that the manifold admits $(f, g, A_1, A_2, T_1, T_2)$ - Hsu metric structure [2].

If V_m is submanifold of V_n ($m < n$), then V_m is called invariant submanifold of V_n if F leaves invariant the tangent space of V_m at all points. If all X tangents to V_n , FX contains tangential and normal points to V_m both then V_m is non invariant submanifold of V_n .

2. Submanifolds of codimension 2 of the Hsu-metric structure manifold

Let V_n be a Hsu-metric structure manifold with structure (F, G) and V_{n-2} the submanifold of codimension 2 of V_n . So

$$(2.1) \quad F^2 = a^r I_n \quad \text{and} \quad G(FX, FY) = a^r G(X, Y)$$

If 'b' denotes the immersion $V_{n-2} \rightarrow V_n$ and $B = db$, a vector field X tangential to V_{n-2} corresponds to a vector field BX tangent to V_n . Let f be $(1, 1)$ tensor field and 'g' the metric induced on the submanifold and let C_1, C_2 be unit normal fields on the submanifold. Then

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$$(2.2) \quad \begin{aligned} & \text{(i)} \quad G(BX, BY) = g(X, Y) \\ & \text{(ii)} \quad G(BX, C_1) = G(BX, C_2) = 0 \\ & \text{and} \\ & \text{(iii)} \quad G(C_i, C_j) = \delta_{ij} \text{ for } i, j = 1, 2. \end{aligned}$$

Since V_{n-2} is submanifold of codimension 2 of V_n , the transformation equations can be written as

$$(2.3) \quad \begin{aligned} & \text{(i)} \quad FBX = BfX - A_1(X)C_1 - A_2(X)C_2, \\ & \text{(ii)} \quad FC_1 = BT_1 + \lambda C_2, \\ & \text{(iii)} \quad FC_2 = BT_2 + \mu C_1, \end{aligned}$$

where A_1, A_2 are 1-forms, T_1, T_2 vector fields on the submanifold and λ, μ scalars.

Operating (2.3)(i) by F and making use of (2.1) and the equation (2.3) itself, we get

$$a^r BX = Bf^2X - A_1(fX)C_1 - A_2(fX)C_2 - A_1(X)\{BT_1 + \lambda C_2\} - A_2(X)\{BT_2 + \mu C_1\}$$

Comparison of tangential and normal vectors yields

$$(2.4) \quad \begin{aligned} & \text{(i)} \quad f^2 = a^r I_{n-2} + A_1 \otimes T_1 + A_2 \otimes T_2, \\ & \text{(ii)} \quad A_1 \circ f + \mu A_2 = 0, \\ & \text{(iii)} \quad A_2 \circ f + \lambda A_1 = 0, \end{aligned}$$

Operate (2.3)(ii) by F and making use of (2.1) and (2.3) itself, we get

$$a^r C_1 = BfT_1 - A_1(T_1)C_1 - A_2(T_1)C_2 + \lambda\{BT_2 + \mu C_1\}.$$

As $A_i(T_j) + a^r \delta_{ij} = 0$ so above equation takes the form

$$a^r C_1 = BfT_1 + a^r C_1 + \lambda BT_2 + \lambda \mu C_1.$$

Comparison of tangential and normal vector gives

$$(2.5) \quad \begin{aligned} & \text{(i)} \quad fT_1 + \lambda T_2 = 0, \\ & \text{(ii)} \quad \lambda \mu = 0. \end{aligned}$$

In a similar manner, applying F to (2.3)(iii) and proceeding in a similar manner, we get

$$(2.6) \quad \text{(i)} \quad fT_2 + \mu T_1 = 0,$$

$$(ii) \quad \lambda\mu = 0.$$

Now operating (2.4)(i) by f and using (2.5) and (2.6) we obtain

$$(2.7) \quad f^3 - a^r f + \lambda A_1 \otimes T_2 + \mu A_2 \otimes T_1 = 0.$$

Also in view of equations (2.1), (2.2) and (2.3), it follows that

$$(2.8) \quad g(fX, fY) = a^r g(X, Y) + A_1(X)A_1(Y) + A_2(X)A_2(Y).$$

Hence we have the theorem :

Theorem (2.1) The non-invariant submanifold V_{n-2} of codimension 2 of the Hsu-metric structure manifold V_n admits the structure given by equation (2.7) and (2.8).

3. Submanifolds of codimension 2 of $(f, g, A_1, A_2, T_1, T_2)$ - Hsu metric manifold.

Now suppose that the enveloping manifold admits $(f, g, A_1, A_2, T_1, T_2)$ - Hsu metric structure. Hence equations (1.3) and (1.4) are satisfied. Suppose T_1, T_2 are no where tangents to the submanifold. The transformation equations can be written as

$$(3.1) \quad fBX = B\tilde{f}X - \alpha_1(X)T_1 - \alpha_2(X)T_2$$

where α_1, α_2 are 1-forms on the submanifold and \tilde{f} the induced $(1, 1)$ tensor field.

Operating (3.1) by f and using (3.1) itself and (1.3), we get

$$a^r BX + A_1(BX)T_1 + A_2(BX)T_2 = B\tilde{f}^2 X - \alpha_1(\tilde{f}X)T_1 - \alpha_2(\tilde{f}X)T_2$$

Comparison of tangential vectors gives

$$\tilde{f}^2(X) = a^r X.$$

Hence we have

Theorem (3.1) The non-invariant submanifold of codimension 2 of $(f, g, A_1, A_2, T_1, T_2)$ - Hsu structure manifold where T_1, T_2 are never tangents to the submanifold admits the Hsu-structure.

Let D be the Riemannian connection on the enveloping manifold. Then

$$(3.2) \quad (i) \quad D_{BX}T_1 = -fBX + \lambda T_2 = -B\tilde{f}(X) + \alpha_1(X)T_1 + \alpha_2(X)T_2 + \lambda T_2$$

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$$(ii) \quad D_{BX}T_2 = fBX + \mu T_1 = B\tilde{f}(X) - \alpha_1(X)T_1 - \alpha_2(X)T_2 + \mu T_2$$

Further the Gauss and Wengaster equations are given by

$$(3.3) \quad D_{BX}BY = B(\bar{D}_X Y) + h_1(X, Y)C_1 + h_2(X, Y)C_2,$$

$$(3.4) \quad (i) \quad D_{BX}C_1 = -BH_1X + W_1(X)C_2,$$

$$(ii) \quad D_{BX}C_2 = BH_2X + W_2(X)C_1.$$

where W_1, W_2 are 1-forms on the submanifold and H_1, H_2 tensor fields of type $(1, 1)$ satisfying

$$(3.5) \quad g(H_1X, Y) = h_1(X, Y), \quad g(H_2X, Y) = h_2(X, Y)$$

and \bar{D} the Riemannian connection induced on the submanifold. As T_1, T_2 are never tangents to the submanifold, so comparison of (3.2) and (3.4) gives

$$(3.6) \quad (i) \quad -B\tilde{f}(X) + \alpha_1(X)T_1 + \alpha_2(X)T_2 + \lambda T_2 = -BH_1X + W_1(X)C_2$$

$$(ii) \quad B\tilde{f}(X) - \alpha_1(X)T_1 - \alpha_2(X)T_2 + \mu T_1 = BH_2X + W_2(X)C_1$$

Comparing tangential and normal vectors, we get

$$H_1 = H_2 = \tilde{f} \quad \text{and} \quad W_1(X) = +\alpha_2(X) + \lambda, \quad W_2(X) = -\alpha_1(X) + \mu$$

Hence we have

Theorem (3.2) For a submanifold of codimension 2 of a $(f, g, A_1, A_2, T_1, T_2)$ - Hsu metric structure manifold, we have $H_1 = H_2 = \tilde{f}$ and $W_1(X) = +\alpha_2(X) + \lambda, W_2(X) = -\alpha_1(X) + \mu$ where \tilde{f} is induced $(1, 1)$ tensor field on the submanifold.

Since A_1, A_2 are 1-forms on the enveloping manifold and α_1, α_2 induced 1-forms on the submanifold, hence $A_1(BX) = \alpha_1(X), A_2(BX) = \alpha_2(X)$

If \tilde{g} be the metric induced on the submanifold

$$(3.7) \quad g(BX, BY) = \tilde{g}(X, Y)$$

Now

$$g(fBX, fBY) = g(B\tilde{f}(X) - \alpha_1(X)T_1 - \alpha_2(X)T_2, B\tilde{f}(Y) - \alpha_1(Y)T_1 - \alpha_2(Y)T_2)$$

or

$$(3.8) \quad g(fBX, fBY) = g(B\tilde{f}X, B\tilde{f}Y) + \alpha_1(X)\alpha_1(Y) + \alpha_2(X)\alpha_2(Y).$$

In view of the equations (2.8) and (3.7), we get

$$\begin{aligned} & a^r g(BX, BY) + A_1(BX)A_1(BY) + A_2(BX)A_2(BY) \\ & = g(B\tilde{f}X, B\tilde{f}Y) + \alpha_1(X)\alpha_1(Y) + \alpha_2(X)\alpha_2(Y) \end{aligned}$$

or

$$(3.9) \quad \tilde{g}(\tilde{f}X, \tilde{f}Y) = a^r \tilde{g}(X, Y)$$

It has already been shown that

$$\tilde{f}^2(X) = a^r X$$

Thus we have

Theorem (3.3) A non-invariant submanifold of codimension 2 of a $(f, g, A_1, A_2, T_1, T_2)$ - Hsu metric structure manifold admits the Hsu metric structure.

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